

Thankyou for choosing Yeah Racing Products. Welcome to the power and convenience of Brushless RC. By purchasing the Hacktronic G2 Competition Brushless Electronic Speed Control ("ESC") you have chosen one of the most advanced speed controls in RC Racing. The G2 allows customization for multiple programmable parameters (using the ESC's Program Card which can be purchased separately). Please read this manual thoroughly to familiarize yourself with the installation, setup and operation. By operating this product, you accept the Yeah Racing Warranty Terms.

Specification

- *** 32 bit processor
- *** Continuous current
- System: Forward/Brake/Reverse
- Weight
- Voltage Input
- Peak Current
- Motor Limit:
- Motor Type
- B.E.C.:
- Multi Protection System

Yes (Factory preset at Forward/Brake) 33.3(L) x 41(W) x 20.8(H)mm

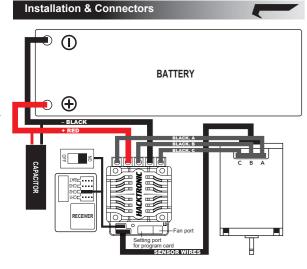
- 43g (excluding wires) (4.8 - 9.9V DC)
- 6 Cells NiCD/NiMH 2-Cell LiPO / 2-3 Cell LiFe 570A

*** Low resistance FFT

*** Auto Fan control

Brushless

- Over 5.5 Turns
- Sensored 540 sized brushless motors 5A 6V/7.2V



- Position the ESC where it is protected in the event of a crash. Use the supplied double sided tape to secure the ESC to the chassis.
- · Install/Solder the relevant battery connector (Battery Specific) to the battery wires. RED to +ve and BLACK to -ve. (WARNING! Reversing the battery polarity will destroy your ESC and void the warranty.)
- Connect supplied BEC wire(100mm) to 3pin port match the "- + s" between the receiver connector and ESC.
- · Connect the 3 motor wires to the motor; you can either solder the wires directly to the motor or use your favorite connectors. Match the label of the ESC Output (A, B, C) to the Tab labels on the motor when soldering. Avoid soldering each joint for longer than 5 seconds. Prior to operation make sure you have not created a short by either creating a wire bridge or solder bridge on the solder tabs on the motor. (WARNING! Improper wiring may damage the ESC and void the
- Connect the sensor cable between the ESC sensor plug and the Motor sensor
- · Connect the receiver plug to the CH2/throttle pin of the receiver

- · The Fan port voltage is drawn directly from the battery.
 - The Motor configuration A-B-C can be changed to C-B-A in the "ESC motor link". Enter program and before setup of the program. Ensure that your physical wiring configuration of A-B-C match the Initial Setup options of the Program Card. (WARNING! Improper configuration may damage the ESC.)

Radio & ESC set-up



Transmitter Settings

Throttle Trave Maximum / 100% Brake Travel Maximum / 100% Start with 0% Throttle Exponentia Throttle Neutral Trim Center / 0 Throttle Servo Reverse Reverse (Futaba, KO, Sanwa)

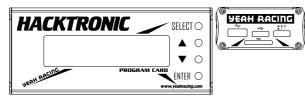
Initial set-up of the throttle end-points of the ESC:

- · Connect the power wires of the ESC to a fully charged battery set; making sure the polarity is correct.
- · Bind your receiver and transmitter first if your radio requires you to do so
- Turn on the transmitter and hold the throttle at full brake position
- · Turn on ESC and listen for 2 beeps
- After you hear the 2 beeps, apply full throttle and listen for another 2 beeps.
- Once you hear the 2 beeps, release the throttle to neutral position.
- · A beep will then sound, signifying that the ESC endpoints have been

Note! If you do not hear the beeping sound as described above, try reversing the throttle reverse setting in the transmitter

Customizing the ESC

Due to the different requirements of each style and class of racing, it is important to customize your ESC for each use case. Customization of the ESC is done using the Program Card (Sold Separately):



To begin, connect the battery wires to a charged battery, then connect supplied 4pin wire (200mm) to the ESC setting port (4pin port) and Program Card. Turn on the ESC and the Program Card will activate automatically. Note that the screen will show "Loading..." during initialization - indicating that the ESC is copying the current setup in the ESC to the Program Card. Once loading is completed, the screen will show "HACKTRONIC G2" and "Program". You can now begin programming your ESC

Press "Enter" to access Program Mode or Data Reading.

There are 4 Modes available: Blinky, Modified, Open Stock Brushless and Offroad profiles are pre-loaded within the firm-ware

TIPS! Whenever in doubt, double check your ESC setting by initializing the Program Card again and checking each menu setting

Navigation around the Program Menu is done using the 4 buttons on the right hand side of the Program Card. The function of each button varies depending on which screen the display is showing:

"Select" button-----ao to next select

Press and Hold "Select" button two second -----go to back page

- "A" button "▼" button
- Scroll up - Scroll down
- "Enter" button

- Send Changes from Program Card to the ESC and overwrite old data in the ESC

NOTE! The Program Card is not included and is sold separately

The Program Card will compare the Parameters within the card and ESC before sending. If changes are detected, you will hear a series of beeps and the Program Card will display:

Send Success

TIPS! Do not worry about making mistakes. You will not damage the ESC during setting. If in doubt, you can always reload the default set up and start over again

Operation

Getting started

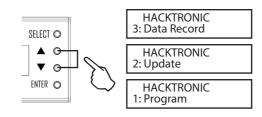
Turn on the on/off switch, the screen will display



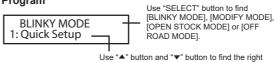
Use "▲" button and "▼" button to find [Program], [Update] or [Data Record]

Press "" button to choose. Each mode presented are independent from each other and will require setup

Press "SELECT" button for 2 seconds to go back to the previous screen.



1. Program



Press "__" button to set up your ESC after you choose the right motor link

2. Update

Updating of ESC Firmware:

Scroll to the "Update" menu and press "Enter". This will show the current ESC FW Version. Press "Enter" again to access the SD cards Firmware folder. Select the FW Version that you would like to use to update the ESC. Press "Enter" again and the update will commence (It will take around 1 minute to complete the

Updating of Program Card Firmware:



Depress and hold the Program card's "Enter" button while turning on the ESC. It will display the current Program card FW Version. Press "Enter" again to access the SD cards Firmware folder. Select the FW Version that you would like to use to update the Program Card. Press "Enter" again and the update will commence (It will take around 1 minute to complete the update).

Preparing the SD card for use:

Format a microSD card using FAT32 file structure using a personal computer. If you are using a Micro SD Card larger than 32GB, you will need to use a 3rd party SW Package to do this. Create a new folder called "Firmware". Download the latest firmware from http://www.yeahracing.com/catalog/YR_Download_Page.htm and copy the file to the "Firmware" folder on the Micro SD card.

Once completed, install the MicroSD card into the microSD card slot of the Program Card. Both the Program Card and ESC FW Files need to be copied in to the "Firmware" Folder. A maximum of 10 of each ESC/Program card firmware can be present in the folder at any one time.

3. Data Record



This will show the last pack of run, the min Battery Voltage, max ESC Temperature max Motor Temperature

Please double press "". Enter button to clear the data, otherwise this data will

Operating Tips



Multi Protection System - In addition to the Low Voltage and Overheat Protection that were described above, the ESC is protected in 2 more ways.

Motor Lock Protection:

- The ESC is protected against damage when the motor is stuck and does not turn at all. Power will not be applied in this situation.
- CAUTION! Since the ESC relies on the feed back of the 3 motor wires to deploy this protection, it ONLY works if the motor does not turn AT ALL. If the rotor has any rotation, the ESC will consider the motor to be operational and the power to the motor will not be cut off.

Fail Signal Protection:

In case the radio signal to the ESC is interrupted for over 1 second during a run, the ESC will cut off until the signal resumes.

ROAR Stock Spec Racing:

ROAR has announced the new class of Stock Spec Racing using a zero degree timing ESC with Spec Motors known commonly as 'Blinky' classes. The G2 ESC satisfies the ROAR requirement showing a blinking LED when set at 0 timing and 0 turbo timing.

- · Connect the ESC to the battery pack only when you are ready to run. This will avoid draining the battery pack. Always disconnect the battery after your run.

 • A small spark may occur when the battery is initially connected to the ESC. This
- is normal and is due to the charging of the capacitors

1. Program		
	A + B – C	
	C + B – A	

1. Program / E	Blinky Mode		
	1.Punch	Level:1-15	14
Quick Setup	2.Pulse Width Modulation (PWM)	2000-32000Hz	8000HZ
Quion Cotup	2 DrogProko	OFF	6%
	3.DragBrake	1%-30%	
	4.Compress	0%-50%	18%
		-5	
		-4	
		-3	
		-2	
		-1	
	1.PunchFineTune	Normal	Normal
		+1	1
Advance Setup		+2	
		+3	
		+4	_
		+5	
	2.BrakeFreq	200-5000Hz	1000Hz
	3.InitialBrake	0-60%	60%
	4.Initial Brake range	0-100%	50%
	5.MaxbrakeForce	0-100%	100%
		Forward/Brake	
	1.RunningMode	Forward/Rev	Forward/Bral
	1.Ruillingwode	For/Brake/Rev] Torwara, Brai
		For/Hold/Rev	
		LiPolymer	
	2.Battery	LI-FE	LiPolymer
		NI-XX	
		OFF	1
	3.CutOffVolage	LOW 2.9v/s	OFF
	-	MIDDLE 3.2v/s	
		HIGH 3.4v/s	
		95°	-
	4.EscOverHeat	105°	120°
		120°	
		No Protection	
Initial Setup		95°	-
	5.MotorOverHeat	105°	120°
		120°	-
	0.11 / 15	No Protection	50/
	6.NeutralRange	2%-15%	5%
		Auto	-
	7 Fan Mada	40%	10070
	7.Fan Mode	60%	
		80%	
		100%	
	8.BEC Voltage 9.MotorAction	7.2V	6V
		CCW	
		CW	CCW

Detailed Explanation of each ESC Menu items

Quick Setup:

- 1. Throttle Feel Throttle response more soften (1) More Aggressive (5) Touring lor. 8000 for (1-2) bugget for (4-5) 2. **Punch** – Allows you to change the punch of the ESC (Level 1 to Level 15):
- Level 1 has the least punch and Level 15 has the highest punch.
- Adjust punch level to maximize acceleration speed with minimum wheel
- 3. Timing (Except "Blinky Mode") Allows you to adjust the timing of the motor (0°-100° Mode 1° increments): Generally speaking, in brushless systems, an increase in timing will result
- in an increase in the RPM of the motor. However, increase in timing can also decrease the efficiency of the system, thus generating heat on the ESC and motor
- Lower timing has the most torque and the lowest RPM; Higher timing has the least torque and the highest RPM.
- Turbo Timing (Except "Blinky Mode") Turbo Timing is unique to brushless systems because the ESC can simulate motor timing advance. While mechanical timing advance in a brushed motor system is limited by the physical phasing of the motor, brushless ESC timing advance can push beyond that physical limit. As a result, motors can run at a super-high RPM in the Turbo Timing mode, resulting in a sensation of having a 2nd gear/Turbo for top speed. This menu allows you to adjust the amount of Turbo Timing in your ESC in 1º increments. (The "Turbo Timing" should never be greater in value than Timing)
- 5. **Turbo down rank** (Except "Blinky Mode") This is an opposite side Turbo timing for braking, preset -10, if you set the value to -1, this will smooth the throttle response as you slow from top speed, if you value set to -30, this will have more drag brake effect when you release throttle from top speed.

1.Throttle Feel 1-5	1. Program / I	Modified Mode		
Advance Setup Advance Setup Altribo Jiming Altribo Jiming 5. Turbo Jiming 1. Punch Fine Tune 1. Punc			1-5	1
A.TurboTiming	Quick Setup			4
Quick Setup 4.TurboTiming		3 Timing	OFF	10
A. Turbo DownRake		5. Hilling	100°	10
Quick Setup S.TurboDownRake Fastest (-1)-(-30) -20		4 TurboTiming	OFF	48
1.PunchFineTune				
6.DragBrake OFF 1%-30% 12 1.PunchFineTune		5.TurboDownRake		-20
1.PunchFineTune				
1.PunchFineTune		6.DragBrake		12
1.PunchFineTune			1%-30%	
1.PunchFineTune			-5	
1.PunchFineTune				-
1.PunchFineTune			-3	-
1.PunchFineTune			-2	
1-1			-1	
Advance Setup 1-2		1.PunchFineTune	Normal	Normal
Advance Setup Company			+1	
Advance Setup Advance Setup				
Advance Setup 1-5				
2.Pulse Width 2000-32000 10000 3.Compress 0%-50% 2% 4.TimingStart 0%-90% 50% 5.TimingRange 0.50% 45% 6.TurboDelay 7.TurboStart 40%-100% 92% 7.TurboStart 40%-100% 92% 7.TurboStart 40%-100% 92% 8.TurboPunch 10				
Modulation (PWM) 2000-32000 10000			+5	
3.Compress 0%-50% 2% 4.TimingStart 0%-90% 50%			2000-32000	10000
Advance Setup		, ,	0%-50%	2%
S.TimingRange				
Advance Setup 6.TurboDelay 7.TurboStart 40%-100% 92% -5 -4 -3 -3 -2 -1 -1 Normal +1 +2 +3 +4 +5 9.BrakeFreq 800-5000Hz 10.InitialBrake -60% 34% 11.Initial Brake range 12.MaxbrakeForce 1.RunningMode 12.MaxbrakeForce 1.RunningMode				
7.TurboStart 40%-100% 92% 7.TurboStart 40%-100% 92% -5 -4 -3 -3 -2 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1	Advance Setup			
S.TurboPunch		6. I urboDelay	0.01s	0.02s
A		7.TurboStart	40%-100%	92%
S.TurboPunch S.Tu			-5	
8. TurboPunch			-4]
S.TurboPunch			-3	
8.TurboPunch				
+1				
+2		8.TurboPunch		Normal
+3			· ·	
+4				
+5				
9.BrakeFreq 800-5000Hz 1300 10.InitialBrake 0-60% 34% 11.Initial Brake range 0-100% 74% 12.MaxbrakeForce 0-100% 74% 12.MaxbrakeForce 0-100% 74% Forward/Brake Forward/Rev For/Brake/Rev For/Brake/Rev Forl/Brake/Rev For/Hold/Rev LiPolymer 2.Battery LiFE NI-XX OFF NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection 120° No Protection 6.NeutralRange 2%-15% 6% Auto 40% 7.Fan Mode 60% 100% 8.BEC Voltage 6V 7V 7V 9.MotorAction CCW CCW CCW				
10.InitialBrake		9.BrakeFreq		1300
12.MaxbrakeForce		10.InitialBrake	0-60%	34%
1.RunningMode		11.Initial Brake range	0-100%	30%
1.RunningMode		12.MaxbrakeForce	0-100%	74%
1.RunningMode			Forward/Brake	Forward/Brake
Fol/Blake/Rev For/Hold/Rev LiPolymer LiPolymer LiPolymer LiPolymer LiPolymer NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection 95° 105° 120° No Protection 6.NeutralRange 2%-15% 6% Auto 40% 7.Fan Mode 60% 100% 8.0% 100% 8.0% 100% 8.0% 100% 9.MotorAction CCW		1.RunningMode		
LiPolymer Li-FE LiPolymer				
2.Battery				
NI-XX		-	-	LiBahasa
3.CutOffVoltage				LiPolymer
3.CutOffVoltage				
A.EscOverHeat				-
HIGH 3.4v/s 95° 105° 120° 1				OFF
4.EscOverHeat				
120° 120°		4 FacOverl last	95°	
120° No Protection 95° 105° 120° 1			105°	120°
S.MotorOverHeat		4.ESCOVETHEAL	120°	120
5.MotorOverHeat			No Protection	
5.MotorOverHeat 120° No Protection 6.NeutralRange 2%-15% 6% Auto 40% 7.Fan Mode 60% 100% 80% 100% 8.BEC Voltage 6V 7V 9.MotorAction 120° No Protection 6% 6% 6% Auto 40% 60% 100% 60% 100% 60% 70 GCW	Initial Setup	5.MotorOverHeat	95°	
120°			105°	120°
6.NeutralRange 2%-15% 6% Auto 40% 7.Fan Mode 60% 100% 80% 100% 8.BEC Voltage 6V 7V 9.MotorAction CCW CCW				120
Auto 40% 7.Fan Mode 60% 100% 80% 100% 8.BEC Voltage 6V 7V 9.MotorAction CCW CCW CCW				
7.Fan Mode		ნ.NeutralRange		6%
7.Fan Mode 60% 100% 80% 100% 8.BEC Voltage 6V 6V 7V 6V 9.MotorAction CCW CCW				-
8.0% 100% 8.BEC Voltage 6V 7V 9.MotorAction CCW CCW CCW				100%
100% 6V 6V 7V 9 MotorAction CCW CC				
8.BEC Voltage 6V 6V 7V 6V 9.MotorAction CCW CCW				†
8.BEC Voltage 7V 6V 9.MotorAction CCW CCW				
9.MotorAction CCW CCW		8.BEC Voltage		6V
9.MOTOLACTION CM		O MotorAction		CCM
		a.iviotol Action	CW	CCvv

- 6. Drag Brake Also known as trail braking allows you to set the automatic brake force applied when the throttle returns to neutral position (30 steps from 0% to 30%):
- Drag Brake affects how a car handles off-throttle (entering a corner). With drag brake on, there will be more weight shift to the front tires thus increasing the front end grip when you let go the throttle.

 • Experiment with different settings to find the setting that fits your driving

AdvanceSetup 1.Throttle Feel	1. Program / 0	Open Stock Mode		
AdvanceSetup A.TurboTirning G.TurboDownRake 6.DragBrake 1.PunchFineTune 1.PunchFineTun		1.Throttle Feel	1-5	3
AturboTiming 100° 100 100 100 100 100 100 100 100 10	Quick Setup			13
Quick Setup		3 Timing	OFF	15
## A. Turbo Liming 100° 100° 100° 5. TurboDownRake Fastest (-1)+(-30) -10 (-1)+(-1)+(-30) 6. DragBrake OFF 19%-30% 0 1. PunchFineTune Normal +1 +2 +3 +4 +5 2. Pulse Width Normal +1 +2 +3 +4 +5 2. Pulse Width Modulation (PWM) 2000-32000 8000 8000 3. Compress 09%-50% 15% 25% 5. TimingStart 09%-90% 25% 5. TimingRange 0-50% 45% 0.01s 0.02s 0.02s 0.02s 0.01s 0.02s 0.02s 0.02s 0.01s 0.02s 0.02s 0.02s 0.02s 0.02s 0.02s 0.01s 0.02s 0.02s 0.02s 0.02s 0.02s 0.01s 0.02s 0.		5. Filling	100°	45
S.TurboDownRake		4 TurboTiming	OFF	100
S. TurboDownRake (-1)-(-30) -10			100°	.00
6.DragBrake OFF 196-30% 0 1.PunchFineTune		5.TurboDownRake		-10
AdvanceSetup Auto AdvanceS				
1.PunchFineTune		6.DragBrake		0
1.PunchFineTune			1%-30%	
1.PunchFineTune			-5	
1.PunchFineTune				-
1.PunchFineTune				-
1.PunchFineTune				
+1			-1	
+2		1.PunchFineTune	Normal	Normal
1-3			+1	
AdvanceSetup +4			+2	
1-2 2. Pulse Width Modulation (PWM) 2000-32000 8000			+3	
2.Pulse Width Modulation (PWM) 2000-32000 8000			+4	
Modulation (PWM) 2000-32000 6000 3. Compress 0%-50% 15% 4. TimingStart 0%-90% 25% 5. TimingRange 0.50% 45% 0.01s 0.02s 7. TurboStart 40%-100% 92% -4 -3 -2 -1 1.			+5	
AdvanceSetup 4.TimingStart 5.TimingRange 0-50% 45% 45% 6.TurboDelay 6.TurboDelay 7.TurboStart 40%-100% 92% 92% -5			2000-32000	8000
A.TimingStart 0%-90% 25% 5.TimingRange 0.50% 45% 45% 6.TurboDelay 0.01s 7.TurboStart 40%-100% 92% -5 -4 -3 -2 -1 Normal +1 +2 +3 +4 +5 9.BrakeFreq 800-5000Hz 1300Hz 10.InitialBrake 0.60% 30% 12.MaxbrakeForce 0.100% 74% Forward/Rev For/Brake/Rev For		3.Compress	0%-50%	15%
AdvanceSetup 6.TurboDelay 7.TurboStart 40%-100% 92% -5 -4 -3 -2 -1 8.TurboPunch Normal +1 +2 +3 +4 +5 9.BrakeFreq 10.InitialBrake 11.Initial Brake range 12.MaxbrakeForce 1.RunningMode 12.MaxbrakeForce 1.RunningMode 12.Battery 1.FE LiPolymer LiFE LiPolymer LiPolymer LiFE LiPolymer A.EscOverHeat 105° 105° 120° No Protection 106% 120° No Protection 6.NeutralRange 2.Sattery 1.Tan Mode 60% 7.Fan Mode 8.BEC Voltage 6V 7.2V CCCW		4.TimingStart	0%-90%	25%
7.TurboStart		5.TimingRange		45%
7. TurboStart 40%-100% 92% 7. TurboStart 40%-100% 92% -5 -4 -3 -2 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1	AdvanceSetup	6 TurboDelay	OFF	0.02s
B.TurboPunch		o. raibobolay		0.020
A		7.TurboStart		92%
S.TurboPunch S.Tu				
8.TurboPunch				
S.TurboPunch				
8.TurboPunch Normal				-
+1		9 TurboDunoh		
+2		8.TurboPunch		+3
+3				
H4				
9.BrakeFreq 800-5000Hz 1300Hz 10.InitialBrake 0-60% 34% 11.Initial Brake range 0-100% 74% 12.MaxbrakeForce 0-100% 74% Forward/Brake Forward/Rev For/Brake/Rev For/Brake/Rev For/Brake/Rev For/Hold/Rev LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v's 95° 105° 120° No Protection 95° 105° 120° No Protection 6.NeutralRange 2%-15% 6% Auto 40% 7.Fan Mode 60% 100% 8.BEC Voltage 6V 7.2V 6CCW 6V				
10.InitialBrake			+5	
11.Initial Brake range		9.BrakeFreq	800-5000Hz	1300Hz
12.MaxbrakeForce		10.InitialBrake	0-60%	34%
1.RunningMode		11.Initial Brake range	0-100%	30%
1.RunningMode		12.MaxbrakeForce	0-100%	74%
1.RunningMode For/Brake/Rev Forward/Brake Forward/Brake For/Brake/Rev For/Hold/Rev LiPolymer				Forward/Brake
For/Hold/Rev LiPolymer		1 PunningMode	Forward/Rev	
LiPolymer		1.RunningMode		
2.Battery				
NI-XX				
OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v's 95° 105° 120° No Protection 120° No Protection 6.NeutralRange 2%-15% 6% Auto 40% 7.Fan Mode 60% 100% 8.BEC Voltage 6V 7.2V CCW CCW OFF Core		2.Battery		LiPolymer
3.CutOffVoltage				
MIDDLE 3.2v/s HIGH 3.4v's 95° 105° 120° No Protection 120° 120° 120° 120° 120° 120° 120° 120° 120° 120° 120° 120° 120° 120° 120° 120° 120° 120° No Protection 6.NeutralRange 2%-15% 6% Auto 40% 7.Fan Mode 60% 100% 80% 100% 8.BEC Voltage 6V 7.2V 6CCW				-
HIGH 3.4v's 95° 105° 120° 1		3.CutOffVoltage		OFF
4.EscOverHeat				-
4.EscOverHeat				
A.EscOverHeat				1
No Protection 95° 105° 120° 120° 1		4.EscOverHeat		120°
Setup 95° 105° 120°			-	-
5.MotorOverHeat	Initial Setup			120°
120° 120°	•	E Mataron I I t	105°	
6.NeutralRange 2%-15% 6% Auto 40% 7.Fan Mode 60% 100% 80% 100% 8.BEC Voltage 6V 7.2V CCW		o.ivioloi OverHeat		
Auto 40% 7.Fan Mode 60% 80% 100% 8.BEC Voltage 6V 7.2V 6CCW			No Protection	
7.Fan Mode 60% 100% 80% 100% 8.BEC Voltage 6V 6V 7.2V 6V		6.NeutralRange	2%-15%	6%
7.Fan Mode 60% 100% 80% 100% 80% 6V 7.2V 6V				
8.0% 100% 8.BEC Voltage 6V 7.2V 6V			40%	
8.BEC Voltage 6V 7.2V 6V				
8.BEC Voltage 6V 7.2V 6V				
8.BEC Voltage 7.2V 6V				
7.2V		8.BEC Voltage		6V
L L GGVV				
9.MotorAction CCW		9.MotorAction		ccw
CVV			CVV	

Advance Setup:

- Punch fine tune Allows you fine tune your Punch setting more detail, if you set (+1) your punch will up to 7.1 when the punch setup is 7, if you set (-1) your punch will down to 6.9 when you setup is 7.
- set (-1) your punch will down to 6.9 when you setup is 7. **Pulse Width Modulation (PWM)** (This function can be found in the "Advance setup" except Blinky mode) Allows you to change the forward drive frequency of the ESC (2K to 32K step by 500HZ)
- The 2K setup will give you good punch at the low end
- The 32K setup will result in strong mid to top end.

	Off Road Mode		
	1.Throttle Feel	1-5	5
	2.Punch	Level:1-15	11
	3.Pulse Width Modulation (PWM)	2000-32000Hz	8000Hz
Quick Setup	4.Timing	OFF 100°	- 4
		OFF	
	5.TurboTiming	100°	off
	6 D D I	OFF	3
	6.DragBrake	1%-30%	3
		-5	
		-4	
		-3	
		-2	
		-1	
	1.PunchFineTune	Normal	Normal
		+1	
		+2	
		+3	
		+4	
	2 Daysess Fares	+5	250/
	2.ReverseForce 3.Compress	0%-100% 0%-50%	35% 10%
	4.TimingStart	0%-50%	55%
	5.TimingStart	0-50%	45%
AdvanceSetup	5. Tilling Range	OFF	4370
AdvanceSetup	6.TurboDelay	0.01s	0.02s
	7.TurboStart	40%-100%	92%
	7.101003ta1t	-5	9270
		-4	-
		-3	
		-2	-
		- <u>-</u>	-
	8.TurboPunch	Normal	Normal
	O. Turbor unon	+1	Nomiai
		+2	
		+3	-
		+4	
		+5	
	9.BrakeFreq	800-5000Hz	2000Hz
	10.InitialBrake	0-60%	35%
	-	0-0070	-
	11 Initial Brake Range	0-100%	
	11.Initial Brake Range	0-100%	50%
	11.Initial Brake Range 12.MaxBrakeForce	0-100%	80%
	12.MaxBrakeForce	0-100% Forward/Brake	80%
		0-100% Forward/Brake Forward/Rev	-
	12.MaxBrakeForce	0-100% Forward/Brake Forward/Rev For/Brake/Rev	80%
	12.MaxBrakeForce	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev	80%
	12.MaxBrakeForce 1.RunningMode	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer	80% Forward/Brake
	12.MaxBrakeForce	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE	80%
	12.MaxBrakeForce 1.RunningMode	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX	80% Forward/Brake
	12.MaxBrakeForce 1.RunningMode 2.Battery	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX	80% Forward/Brake LiPolymer
	12.MaxBrakeForce 1.RunningMode	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s	80% Forward/Brake
	12.MaxBrakeForce 1.RunningMode 2.Battery	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s	80% Forward/Brake LiPolymer
Initial Setun	12.MaxBrakeForce 1.RunningMode 2.Battery	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s	80% Forward/Brake LiPolymer
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95°	80% - Forward/Brake - LiPolymer - OFF
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105°	80% Forward/Brake LiPolymer
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120°	80% - Forward/Brake - LiPolymer - OFF
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105°	80% - Forward/Brake - LiPolymer - OFF
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage 4.EscOverHeat	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPOlymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection	80% Forward/Brake LiPolymer OFF
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev Li/Polymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection 95°	80% - Forward/Brake - LiPolymer - OFF
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage 4.EscOverHeat	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection 95° 105°	80% Forward/Brake LiPolymer OFF
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage 4.EscOverHeat 5.MotorOverHeat	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection 95° 105° 120°	80% Forward/Brake LiPolymer OFF
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage 4.EscOverHeat	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 120° No Protection 95° 120° No Protection	80% Forward/Brake LiPolymer OFF 120°
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage 4.EscOverHeat 5.MotorOverHeat	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection 95° 105° 120° No Protection 2%-15%	80% Forward/Brake LiPolymer OFF 120°
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage 4.EscOverHeat 5.MotorOverHeat	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° No Protection 95° 105° 120° No Protection 2%-15% Auto	80% Forward/Brake LiPolymer OFF 120°
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage 4.EscOverHeat 5.MotorOverHeat 6.NeutralRange	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection 95° 120° No Protection 2%-15% Auto 40% 60%	80% Forward/Brake LiPolymer OFF 120° 6%
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage 4.EscOverHeat 5.MotorOverHeat 6.NeutralRange	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection 95° 105° 120° No Protection 95° 40% Auto 40% 60% 80%	80% Forward/Brake LiPolymer OFF 120° 6%
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage 4.EscOverHeat 5.MotorOverHeat 6.NeutralRange 7.Fan Mode	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection 95° 105° 120° No Protection 2%-15% Auto 40% 60% 80%	80% Forward/Brake LiPolymer OFF 120° 6% 100%
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage 4.EscOverHeat 5.MotorOverHeat 6.NeutralRange	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection 95° 105° 120° No Protection 2%-15% Auto 40% 60% 80% 100% 6V	80% Forward/Brake LiPolymer OFF 120° 6%
Initial Setup	12.MaxBrakeForce 1.RunningMode 2.Battery 3.CutOffVoltage 4.EscOverHeat 5.MotorOverHeat 6.NeutralRange 7.Fan Mode	0-100% Forward/Brake Forward/Rev For/Brake/Rev For/Hold/Rev LiPolymer LI-FE NI-XX OFF LOW 2.9v/s MIDDLE 3.2v/s HIGH 3.4v/s 95° 105° 120° No Protection 95° 105° 120° No Protection 2%-15% Auto 40% 60% 80%	80% Forward/Brake LiPolymer OFF 120° 6% 100%

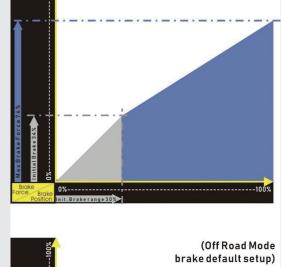
- Experiment to find out what suits your driving style best. (Lower PWM will lower ESC temperatures while higher PWM settings may increase ESC temperatures and Higher PWM will course ESC more heat.) Ensure that your physical wiring configuration of A-B-C
- match Initial Setup options of the Program Card.

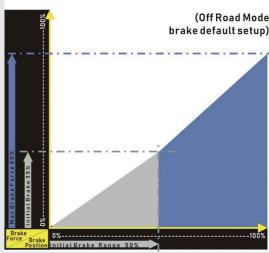
 3. Compress (found in "Advance Setup" menu, Except for Blinky mode where it can be found in "Quick Setup") - This is for throttle curve, the higher the number, the more responsive the throttle feels at bottom end.

0% is linear throttle response. That's mean throttle compress, than will course you more sensitive in the throttle bottom

- Timing start Allows you to adjust early or later to add timing in bottom power, this will make it easy to get a smooth power band in bottom
- Timing range Allows you to adjust a smooth power band in middle
- Turbo delay Delay how long to start your turbo timing when you touch the throttle turbo point.
- Turbo start Allows you to adjust which throttle point to start the turbo and not only full throttle to start turbo and let it easy to get a smooth power hand for all kind of motors
- Turbo Punch let you adjust the top speed power band of turbo, turbo punch + get more aggressive and turbo punch - get more smooth of top
- Brake Freq. Brake Frequency operates similar to PWM except it affects the braking instead of the throttle (100hz / step from 600hz to
- At 1k Hz, the Drag brake and the Brake force will feel the punchiest At 5k Hz, the Drag brake and the Brake will feel very smooth.
- 10. Initial Brake
- 11. Initial Brake range see diagram below.
- 12. Maxbrake Force -







Caution! Always monitor motor and ESC temperatures closely when applying timing to the ESC or motor. Heat may build up very fast in both ESC and motor and may cause permanent damage to equipment.

Limited Warranties / Repair Proceedures

All YR products are manufactured in accordance with the highest quality standards. YR guarantees this product to be free from defects in materials or workmanship for 60 days from the original date of purchase verified by sales receipt. This limited warranty does not cover damages resulting from abnormal wear, misuse or improper maintenance of the product.

To avoid unnecessary service and mailing charges, always eliminate all other possibilities and check all components for malfunctions before sending in your unit for repair. Products sent in for repair that operate perfectly will be charged a service

When sending in the product, always pack carefully and include the original sales receipt, a description of the problem encountered, your return address and contact

Since we do not have control over the installation and use of this product, we cannot accept any liability for any damages resulting from the usage of this product. Therefore, using this product is at your own risk, and the user accepts all resulting liability from installing and using of the product.

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